

## TOPOLOGICAL SPACES AND CONTINUOUS MAPS

SOME MOTIVATION FOR THE GENERAL DEFINITIONS: CONSIDER THE SET

$$\mathbb{R}^3 = \{x = (x^1, x^2, x^3) : x^i \in \mathbb{R}, i=1,2,3\}$$

(EVERYTHING IS THE SAME FOR ANY  $\mathbb{R}^n$ ).

### MATHEMATICAL STRUCTURE :

1. LINEAR (VECTOR SPACE) :  
$$x + y = (x^1, x^2, x^3) + (y^1, y^2, y^3)$$
$$= (x^1 + y^1, x^2 + y^2, x^3 + y^3)$$
$$ax = a(x^1, x^2, x^3), \quad a \in \mathbb{R}$$
$$= (ax^1, ax^2, ax^3)$$
2. INNER PRODUCT :  
$$\langle x, y \rangle = x^1 y^1 + x^2 y^2 + x^3 y^3$$
$$\|x\|^2 = \langle x, x \rangle = (x^1)^2 + (x^2)^2 + (x^3)^2$$
3. METRIC :  
$$d(x, y) = \|y - x\| = \text{DISTANCE BETWEEN } x \text{ AND } y$$
4. TOPOLOGICAL :  
$$U_\varepsilon(p) = \{x \in \mathbb{R}^3 : d(p, x) < \varepsilon\}$$

= OPEN BALL OF RADIUS  $\varepsilon > 0$   
ABOUT  $p \in \mathbb{R}^3$

$$U \subseteq \mathbb{R}^3 \text{ IS } \underline{\text{OPEN}} \text{ IN } \mathbb{R}^3 \text{ IF } \forall p \in U$$
$$\exists \varepsilon > 0 \text{ S.T. } U_\varepsilon(p) \subseteq U$$

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EXERCISE 1 : SHOW THAT THE COLLECTION OF OPEN SETS IN  $\mathbb{R}^3$  HAS THE FOLLOWING PROPERTIES :

(a)  $\emptyset$  AND  $\mathbb{R}^3$  ARE OPEN IN  $\mathbb{R}^3$

(b)  $U_\alpha$  OPEN IN  $\mathbb{R}^3 \forall \alpha \in A \Rightarrow \bigcup_{\alpha \in A} U_\alpha$  OPEN IN  $\mathbb{R}^3$

(c)  $U_1, \dots, U_R$  OPEN IN  $\mathbb{R}^3 \Rightarrow U_1 \cap \dots \cap U_R$  OPEN IN  $\mathbb{R}^3$

RECALL THE FOLLOWING DEFINITION FROM ANALYSIS : A MAP  $f: \mathbb{R}^3 \rightarrow \mathbb{R}^3$  IS CONTINUOUS IF FOR EACH  $p \in \mathbb{R}^3$  AND EACH  $\epsilon > 0 \exists \delta > 0$  S.T.

$$d(p, x) < \delta \Rightarrow d(f(p), f(x)) < \epsilon$$

THEOREM :  $f: \mathbb{R}^3 \rightarrow \mathbb{R}^3$  IS CONTINUOUS IFF INVERSE IMAGES OF OPEN SETS ARE OPEN, I.E., IFF  $\forall$  OPEN  $V$  IN  $\mathbb{R}^3$ ,

$$f^{-1}(V) = \{x \in \mathbb{R}^3 : f(x) \in V\}$$

IS OPEN IN  $\mathbb{R}^3$ .

PROOF :  $\Rightarrow$  ASSUME  $f$  IS CONTINUOUS. LET  $V$  BE OPEN IN  $\mathbb{R}^3$ . WE SHOW THAT  $f^{-1}(V)$  IS OPEN IN  $\mathbb{R}^3$ .

LET  $p \in f^{-1}(V)$ . THEN  $f(p) \in V$ . SINCE  $V$  IS OPEN IN  $\mathbb{R}^3 \exists \epsilon > 0$  S.T.  $U_\epsilon(f(p)) \subseteq V$ .

SINCE  $f$  IS CONTINUOUS  $\exists \delta > 0$  S.T.

$$d(p, x) < \delta \Rightarrow d(f(p), f(x)) < \epsilon$$

I.E.,

$$x \in U_\delta(p) \Rightarrow f(x) \in U_\epsilon(f(p)) \in V$$

I.E.,

$$U_\delta(p) \subseteq f^{-1}(V)$$

AS REQUIRED.

$\Leftarrow$  NOW ASSUME  $f$  SATISFIES  $V$  OPEN  $\Rightarrow f^{-1}(V)$  OPEN

WE SHOW THAT  $f$  IS CONTINUOUS. LET  $p \in \mathbb{R}^3$  AND SUPPOSE

$\epsilon > 0$  IS GIVEN.

$$U_\epsilon(f(p)) \text{ OPEN} \Rightarrow f^{-1}(U_\epsilon(f(p))) \text{ OPEN}$$

SINCE  $p \in f^{-1}(U_\epsilon(f(p)))$ ,  $\exists \delta > 0$  S.T.  $U_\delta(p) \subseteq f^{-1}(U_\epsilon(f(p)))$ .

THUS,

$$x \in U_\delta(p) \Rightarrow f(x) \in U_\epsilon(f(p))$$

I.E.,

$$d(p, x) < \delta \Rightarrow d(f(p), f(x)) < \epsilon$$

AS REQUIRED. □

THE POINT HERE IS THAT "CONTINUITY" CAN BE EXPRESSED ENTIRELY IN TERMS OF "OPEN SETS".

GENERALIZATION MOTIVATED BY THIS :

A TOPOLOGY ON A NONEMPTY SET  $X$  IS A COLLECTION  $\mathcal{J}_X$  OF SUBSETS OF  $X$  WITH THE FOLLOWING PROPERTIES :

$$(a) \quad \emptyset \text{ AND } X \text{ ARE IN } \mathcal{J}_X$$

$$(b) \quad U_\alpha \in \mathcal{J}_X \quad \forall \alpha \in A \Rightarrow \bigcup_{\alpha \in A} U_\alpha \in \mathcal{J}_X$$

$$(c) \quad U_1, \dots, U_k \in \mathcal{J}_X \Rightarrow U_1 \cap \dots \cap U_k \in \mathcal{J}_X$$

THE SETS IN  $\mathcal{J}_X$  ARE CALLED THE OPEN SETS OF THE TOPOLOGY AND  $X$  TOGETHER WITH  $\mathcal{J}_X$  IS CALLED A TOPOLOGICAL SPACE.

IF  $\mathcal{J}_X$  IS A TOPOLOGY FOR  $X$  AND  $\mathcal{J}_Y$  IS A TOPOLOGY FOR  $Y$ , THEN A MAPPING

$$f : X \rightarrow Y$$

IS SAID TO BE CONTINUOUS IF

$$\forall V \in \mathcal{J}_Y \Rightarrow f^{-1}(V) \in \mathcal{J}_X.$$

EXAMPLES :

1. THE COLLECTION OF OPEN SETS IN  $\mathbb{R}^3$  DESCRIBED ABOVE IS THE USUAL (OR EUCLIDEAN) TOPOLOGY FOR  $\mathbb{R}^3$ .

IN EXACTLY THE SAME WAY ONE OBTAINS THE USUAL (OR EUCLIDEAN) TOPOLOGY ON ANY  $\mathbb{R}^n$ .

THE SAME PROOF AS THAT GIVEN FOR  $\mathbb{R}^3$  ABOVE SHOWS THAT ANY MAP

$$f : \mathbb{R}^n \rightarrow \mathbb{R}^m$$

IS "CONTINUOUS WITH RESPECT TO THE USUAL TOPOLOGIES ON  $\mathbb{R}^n$  AND  $\mathbb{R}^m$ " (  $V$  OPEN IN  $\mathbb{R}^m \Rightarrow f^{-1}(V)$  OPEN IN  $\mathbb{R}^n$  )

IF AND ONLY IF IT IS "CONTINUOUS IN THE SENSE OF ANALYSIS" (  $\forall p \in \mathbb{R}^n$  AND  $\forall \epsilon > 0 \exists \delta > 0$  S.T.  $d(p, x) < \delta \Rightarrow d(f(p), f(x)) < \epsilon$  )

THUS, ANYTHING WE KNOW FROM ANALYSIS TO BE CONTINUOUS,

E.G.,

$$f : \mathbb{R}^3 \rightarrow \mathbb{R}^2$$

$$f(x^1, x^2, x^3) = \left( \frac{x^1}{1+(x^3)^2}, \frac{x^2}{1+(x^3)^2} \right)$$

IS CONTINUOUS IN OUR NEW SENSE AS WELL.

EXERCISE 2 : ANY  $X$  CAN BE GIVEN THE DISCRETE TOPOLOGY IN WHICH EVERY SUBSET OF  $X$  IS OPEN ( I.E.,  $\mathcal{T}_X$  IS THE COLLECTION OF ALL SUBSETS OF  $X$  ). VERIFY THAT THIS REALLY IS A TOPOLOGY. NOW, GIVE  $\mathbb{R}^3$  THE DISCRETE TOPOLOGY AND GIVE  $\mathbb{R}^2$  ITS USUAL TOPOLOGY AND FIND ALL OF THE CONTINUOUS MAPS  $f : \mathbb{R}^3 \rightarrow \mathbb{R}^2$  .

2. IF  $X'$  IS A TOPOLOGICAL SPACE WITH TOPOLOGY  $\mathcal{J}_{X'}$ , AND  $X$  IS ANY NONEMPTY SUBSET OF  $X'$ , THEN  $X$  INHERITS A RELATIVE (OR SUBSPACE) TOPOLOGY  $\mathcal{J}_X$  FROM  $X'$  DEFINED BY

$$\mathcal{J}_X = \{U = X \cap U' : U' \in \mathcal{J}_{X'}\}$$

NOTE : THIS REALLY IS A TOPOLOGY FOR  $X$  SINCE

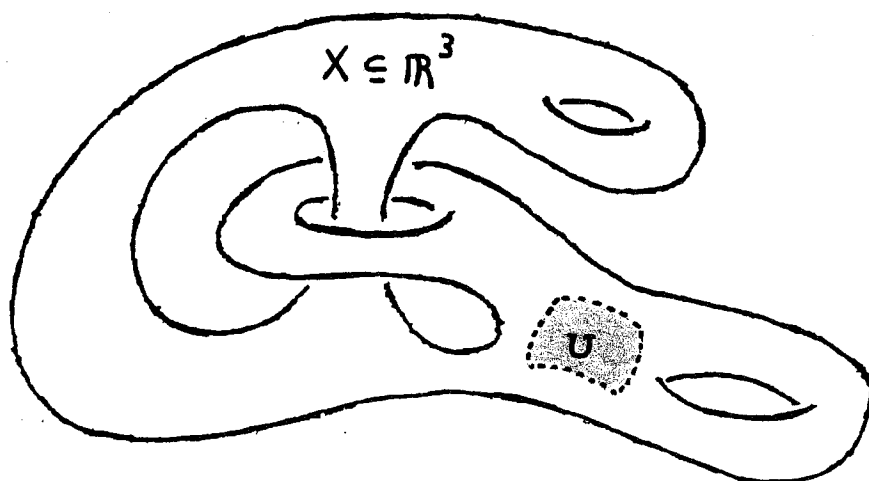
$$X \cap \emptyset = \emptyset$$

$$X \cap X' = X$$

$$\bigcup_{\alpha \in A} (X \cap U'_\alpha) = X \cap \left( \bigcup_{\alpha \in A} U'_\alpha \right)$$

$$(X \cap U'_1) \cap \dots \cap (X \cap U'_n) = X \cap (U'_1 \cap \dots \cap U'_n)$$

E.G., IF  $X \subseteq \mathbb{R}^3$  AND  $\mathbb{R}^3$  HAS ITS USUAL TOPOLOGY, RELATIVE OPEN SETS  $U$  IN  $X$  LOOK LIKE



A SUBSET  $X$  OF  $X'$  WITH THE RELATIVE TOPOLOGY IS CALLED A (TOPOLOGICAL) SUBSPACE OF  $X'$

ANY SUBSET OF ANY EUCLIDEAN SPACE  $\mathbb{R}^n$  CAN THEREFORE BE REGARDED AS A TOPOLOGICAL SPACE, E.G., THE  $n$ -SPHERE

$$S^n = \{ (x^1, \dots, x^{n+1}) \in \mathbb{R}^{n+1} : (x^1)^2 + \dots + (x^{n+1})^2 = 1 \}$$

OTHER IMPORTANT EXAMPLES OF THIS TYPE ARE VARIOUS SETS OF MATRICES.

NOTE : ANY  $m \times n$  REAL MATRIX CAN BE VIEWED AS AN  $mn$ -TUPLE OF REAL NUMBERS :

$$\begin{pmatrix} a^{11} & \dots & a^{1n} \\ \vdots & & \vdots \\ a^{m1} & \dots & a^{mn} \end{pmatrix} \rightarrow (a^{11}, \dots, a^{1n}, \dots, a^{m1}, \dots, a^{mn})$$

SO ANY SET OF REAL MATRICES HAS A TOPOLOGY AS A SUBSPACE OF SOME EUCLIDEAN SPACE.

E.G.,

GENERAL LINEAR GROUP :  $GL(n, \mathbb{R}) =$  ALL  $n \times n$  MATRICES  $A$  THAT ARE NONSINGULAR (INVERTIBLE)

$$= \left\{ A = (a^{ij})_{i,j=1,\dots,n} : a^{ij} \in \mathbb{R}, \det A \neq 0 \right\}$$

IS A TOPOLOGICAL SUBSPACE OF  $\mathbb{R}^{n^2}$ .

NOTE THAT  $\det$ , THOUGHT OF AS A REAL-VALUED FUNCTION ON  $\mathbb{R}^{n^2}$  (I.E., ON  $n \times n$  REAL MATRICES) IS JUST A POLYNOMIAL IN THE ENTRIES (I.E., COORDINATES) SO IT IS CONTINUOUS. THUS,

$$GL(n, \mathbb{R}) = \det^{-1}(\mathbb{R} - \{0\})$$

IS ACTUALLY AN OPEN SUBSPACE OF  $\mathbb{R}^{n^2}$ .

ORTHOGONAL GROUP:  $O(n) =$  ALL  $n \times n$  ORTHOGONAL MATRICES, I.E., THOSE  $A$  SATISFYING

$$A^T A = A A^T = \text{id}_{n \times n}$$

NOTE: THOUGHT OF AS LINEAR TRANSFORMATIONS  $A: \mathbb{R}^n \rightarrow \mathbb{R}^n$  THESE ARE PRECISELY THOSE WHICH PRESERVE THE USUAL INNER PRODUCT  $\langle \cdot, \cdot \rangle$ :

$$\langle Ax, Ay \rangle = \langle x, y \rangle$$

ALSO NOTE THAT

$$\det(AA^T) = \det(\text{id}_{n \times n})$$

$$\det(A) \det(A^T) = 1$$

$$(\det A)^2 = 1$$

$$\det A = \pm 1$$



SPECIAL ORTHOGONAL GROUP :  $SO(n) = \{A \in O(n) : \det A = 1\}$

$O(n)$  AND  $SO(n)$  ARE BOTH TOPOLOGICAL SUBSPACES OF  $\mathbb{R}^{n^2}$   
AND WE CLAIM THAT  $SO(n)$  IS ACTUALLY AN OPEN SET IN  $O(n)$ .

LEMMA : LET  $X$  BE A SUBSPACE OF  $X'$  AND LET  $f : X' \rightarrow Y$   
BE A CONTINUOUS MAP. THEN THE RESTRICTION

$$f|_X : X \rightarrow Y$$

OF  $f$  TO  $X$  IS CONTINUOUS.

PROOF : LET  $V$  BE AN OPEN SET IN  $Y$ . SINCE  $f$  IS CONTINUOUS,  
 $f^{-1}(V)$  IS OPEN IN  $X'$ . THUS,  $X \cap f^{-1}(V)$  IS OPEN IN  $X$ .  
BUT  $X \cap f^{-1}(V) = (f|_X)^{-1}(V)$  SO  $f|_X$  IS CONTINUOUS.  $\square$

THUS, THE RESTRICTION OF  $\det$  TO  $O(n)$  IS CONTINUOUS. SINCE  
 $SO(n)$  IS THE INVERSE IMAGE UNDER THIS CONTINUOUS MAP  
OF  $(0, \infty) \in \mathbb{R}$ , IT IS OPEN IN  $O(n)$ .

EXERCISE 3 : LET  $Y$  BE A SUBSPACE OF  $Y'$  AND  $f : X \rightarrow Y'$  A  
CONTINUOUS MAP WITH  $f(X) \subseteq Y$ . SHOW THAT, THOUGHT OF AS  
A MAP  $f : X \rightarrow Y$  FROM  $X$  TO  $Y$ ,  $f$  IS CONTINUOUS.

EXERCISE 4: LET  $Y$  BE A SUBSPACE OF  $Y'$  AND  $f: X \rightarrow Y$  A CONTINUOUS MAP. SHOW THAT, THOUGHT OF AS A MAP  $f: X \rightarrow Y'$ ,  $f$  IS CONTINUOUS.

EXERCISE 5: LET  $f: X \rightarrow Y$  AND  $g: Y \rightarrow Z$  BE CONTINUOUS MAPS. SHOW THAT THE COMPOSITION  $g \circ f: X \rightarrow Z$  IS CONTINUOUS.

3. THE STANDARD TOPOLOGY ON  $\mathbb{R}^n$  IS DEFINED IN TERMS OF THE "DISTANCE" BETWEEN POINTS IN  $\mathbb{R}^n$  (DISTANCE  $\rightarrow$  OPEN BALLS  $\rightarrow$  OPEN SETS). THIS IS EASY TO GENERALIZE:

LET  $X$  BE A SET. A METRIC ON  $X$  IS A FUNCTION

$$d: X \times X \rightarrow \mathbb{R}$$

THAT SATISFIES

$$(a) \quad d(y, x) = d(x, y) \quad \forall x, y \in X$$

$$(b) \quad d(x, y) \geq 0 \text{ AND } d(x, y) = 0 \text{ IFF } x = y$$

$$(c) \quad d(x, y) \leq d(x, z) + d(z, y) \quad \forall x, y, z \in X$$

THE PAIR  $(X, d)$  IS CALLED A METRIC SPACE. GIVEN ANY  $p \in X$

AND ANY  $\epsilon > 0$  WE DEFINE

$$\begin{aligned}
 U_\varepsilon^d(p) &= \text{OPEN } \underline{d}\text{-BALL OF RADIUS } \varepsilon \text{ ABOUT } p \\
 &= \{x \in X : d(p, x) < \varepsilon\}
 \end{aligned}$$

NOW DEFINE A SET  $U \subseteq X$  TO BE OPEN IF  $\forall p \in U \exists \varepsilon > 0$  S.T.  
 $U_\varepsilon^d(p) \subseteq U$ .

EXERCISE 6 : SHOW THAT THIS DEFINES A TOPOLOGY ON  $X$   
 (CALLED THE METRIC TOPOLOGY).

AS A CONCRETE EXAMPLE, CONSIDER THE SET

$$\begin{aligned}
 C[0, 1] &= \text{ALL CONTINUOUS, REAL-VALUED} \\
 &\quad \text{FUNCTIONS ON } [0, 1]
 \end{aligned}$$

FOR  $f, g \in C[0, 1]$  DEFINE

$$d(f, g) = \max \{ |f(x) - g(x)| : 0 \leq x \leq 1 \}$$

EXERCISE 7 : SHOW THAT THIS REALLY DOES DEFINE A METRIC  
 ON  $C[0, 1]$ .

EXERCISE 8 : DESCRIBE (GEOMETRICALLY) THE OPEN  $\varepsilon$ -BALL  
 ABOUT  $f \in C[0, 1]$  (DRAW A PICTURE).

EXERCISE 9 : LET  $l_\infty(\mathbb{R})$  DENOTE THE SET OF ALL BOUNDED SEQUENCES

$$x = \{x_n\}_{n=1}^{\infty} = \{x_1, x_2, x_3, \dots\}$$

OF REAL NUMBERS. DEFINE

$$d(x, y) = d(\{x_n\}, \{y_n\}) = \sup_n |y - x_n|$$

SHOW THAT THIS DEFINES A METRIC ON  $l_\infty(\mathbb{R})$ .

EXERCISE 10 : A SUBSET  $C$  OF A TOPOLOGICAL SPACE  $X$  IS SAID TO BE CLOSED IN  $X$  IF ITS COMPLEMENT  $X - C$  IS OPEN IN  $X$ . SHOW THAT

(a)  $\emptyset$  AND  $X$  ARE CLOSED IN  $X$

(b)  $C_\alpha$  CLOSED IN  $X \quad \forall \alpha \in \mathcal{A} \Rightarrow \bigcap_{\alpha \in \mathcal{A}} C_\alpha$  CLOSED IN  $X$

(c)  $C_1, \dots, C_k$  CLOSED IN  $X \Rightarrow C_1 \cup \dots \cup C_k$  CLOSED IN  $X$ .

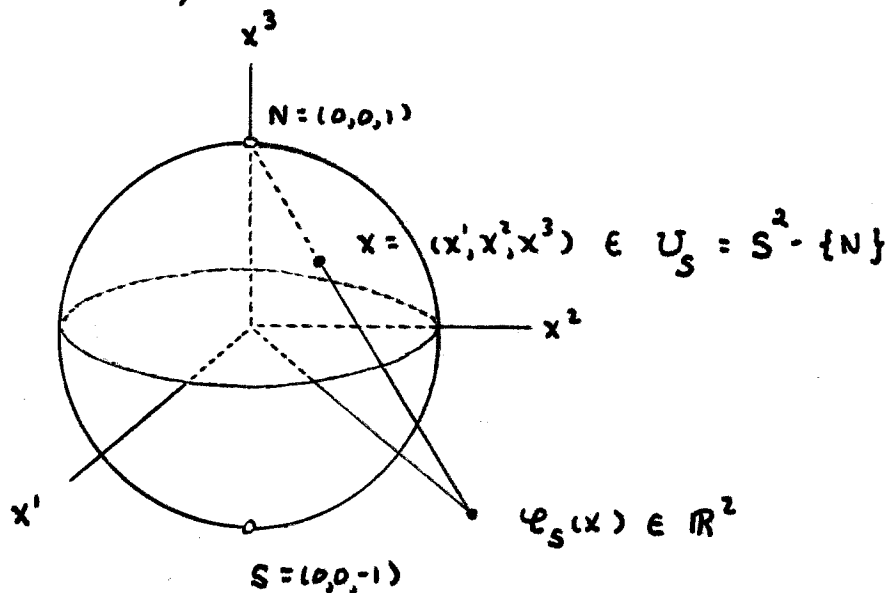
EXERCISE 11 : SHOW THAT  $f : X \rightarrow Y$  IS CONTINUOUS IFF  $C$  CLOSED IN  $Y \Rightarrow f^{-1}(C)$  CLOSED IN  $X$ .

EXERCISE 12 : DESCRIBE AT LEAST ONE "INTERESTING" EXAMPLE OF A CLOSED SET IN EACH OF  $C[0, 1]$  AND  $l_\infty(\mathbb{R})$ .

TO MOTIVATE THE NEXT IMPORTANT IDEA WE COMPUTE AN EXAMPLE.

$$S^2 = \{x = (x^1, x^2, x^3) \in \mathbb{R}^3 : \|x\|^2 = (x^1)^2 + (x^2)^2 + (x^3)^2 = 1\}$$

(WITH ITS RELATIVE TOPOLOGY AS A SUBSPACE OF  $\mathbb{R}^3$ ).



DEFINE

$$U_S = S^2 - \{N\} \quad (\text{AN OPEN SET IN } S^2)$$

$$\varphi_S : U_S \rightarrow \mathbb{R}^2 \quad (\text{STEREOGRAPHIC PROJECTION FROM } N)$$

$\varphi_S(x^1, x^2, x^3) =$  INTERSECTION WITH  $x^3 = 0$  OF THE STRAIGHT  
LINE THROUGH  $N = (0, 0, 1)$  AND  $x = (x^1, x^2, x^3)$

$$= \left( \frac{x^1}{1-x^3}, \frac{x^2}{1-x^3} \right)$$

EXERCISE 13 : PROVE THIS LAST FORMULA.

$\varphi_S$  IS CONTINUOUS ON  $U_S$  (BECAUSE IT IS THE RESTRICTION TO  $U_S$  OF  
A (CALCULUS) CONTINUOUS MAP ON  $\mathbb{R}^3 - \{x^3 = 1\}$ ).

$\varphi_S$  IS ALSO ONE-TO-ONE ON  $U_S$  AND MAPS ONTO  $\mathbb{R}^2$  BECAUSE  
ITS INVERSE IS EASILY FOUND (INTERSECT THE LINE THROUGH  
N AND  $y = (y^1, y^2) \in \mathbb{R}^2$  WITH  $S^2$ ):

$$\varphi_S^{-1} : \mathbb{R}^2 \rightarrow U_S$$

$$\varphi_S^{-1}(y) = \varphi_S^{-1}(y^1, y^2) = \frac{1}{1 + \|y\|^2} (2y^1, 2y^2, \|y\|^2 - 1)$$

$\varphi_S^{-1}$  IS ALSO CONTINUOUS.

$\varphi_S$  "IDENTIFIES"  $U_S$  WITH  $\mathbb{R}^2$

$\varphi_S$  "COORDINATIZES"  $U_S$ , E.G.,  $S = (0, 0, -1)$  IS  
ASSIGNED COORDINATES  
(0, 0) BY  $\varphi_S$ .

SIMILARLY, ONE CAN DEFINE STEREOGRAPHIC PROJECTION FROM S:

$$\varphi_N : U_N = S^2 - \{S\} \rightarrow \mathbb{R}^2$$

$$\varphi_N(x) = \varphi_N(x^1, x^2, x^3) = \left( \frac{x^1}{1+x^3}, \frac{x^2}{1+x^3} \right)$$

$$\varphi_N^{-1} : \mathbb{R}^2 \rightarrow U_N$$

$$\varphi_N^{-1}(y) = \varphi_N^{-1}(y^1, y^2) = \frac{1}{1 + \|y\|^2} (2y^1, 2y^2, 1 - \|y\|^2)$$

GENERAL DEFINITIONS MOTIVATED BY THIS :

IF  $X$  AND  $Y$  ARE TOPOLOGICAL SPACES AND IF THERE EXISTS A CONTINUOUS BIJECTION  $h : X \rightarrow Y$  OF  $X$  ONTO  $Y$  WITH A CONTINUOUS INVERSE  $h^{-1} : Y \rightarrow X$ , THEN  $h$  IS CALLED A HOMEOMORPHISM (AS IS  $h^{-1}$ ) AND  $X$  AND  $Y$  ARE SAID TO BE HOMEOMORPHIC (OR TOPOLOGICALLY EQUIVALENT) AND WE WRITE  $X \cong Y$ .

E.G.,  $U_S$  AND  $U_N$  ARE BOTH HOMEOMORPHIC TO  $\mathbb{R}^2$  (HOWEVER, WE WILL SEE LATER THAT  $S^2$  IS NOT HOMEOMORPHIC TO  $\mathbb{R}^2$ ).

EXERCISE 14 : SHOW THAT  $\cong$  IS AN EQUIVALENCE RELATION ON THE COLLECTION OF ALL TOPOLOGICAL SPACES, I. E.,

$$(a) \quad X \cong X$$

$$(b) \quad X \cong Y \implies Y \cong X$$

$$(c) \quad X \cong Y \text{ AND } Y \cong Z \implies X \cong Z$$

IF  $X$  IS A TOPOLOGICAL SPACE AND  $n$  IS A POSITIVE INTEGER, THEN AN  $n$ -DIMENSIONAL (COORDINATE) CHART ON  $X$  IS A PAIR  $(U, \varphi)$ , WHERE  $U$  IS AN OPEN SET IN  $X$  AND  $\varphi$  IS A HOMEOMORPHISM OF  $U$  ONTO AN OPEN SET  $\varphi(U)$  IN  $\mathbb{R}^n$ .

E.G.,  $(U_S, \varphi_S)$  AND  $(U_N, \varphi_N)$  ARE  
2-DIMENSIONAL CHARTS ON  $S^3$ .

IF  $x \in U$ , THEN  $(U, \varphi)$  IS CALLED A CHART AT  $x$ . IF THERE IS A  
CHART AT  $x$  FOR EVERY  $x \in X$ , THEN  $X$  IS SAID TO BE  
LOCALLY EUCLIDEAN.

E.G.,  $S^2$  IS LOCALLY EUCLIDEAN.

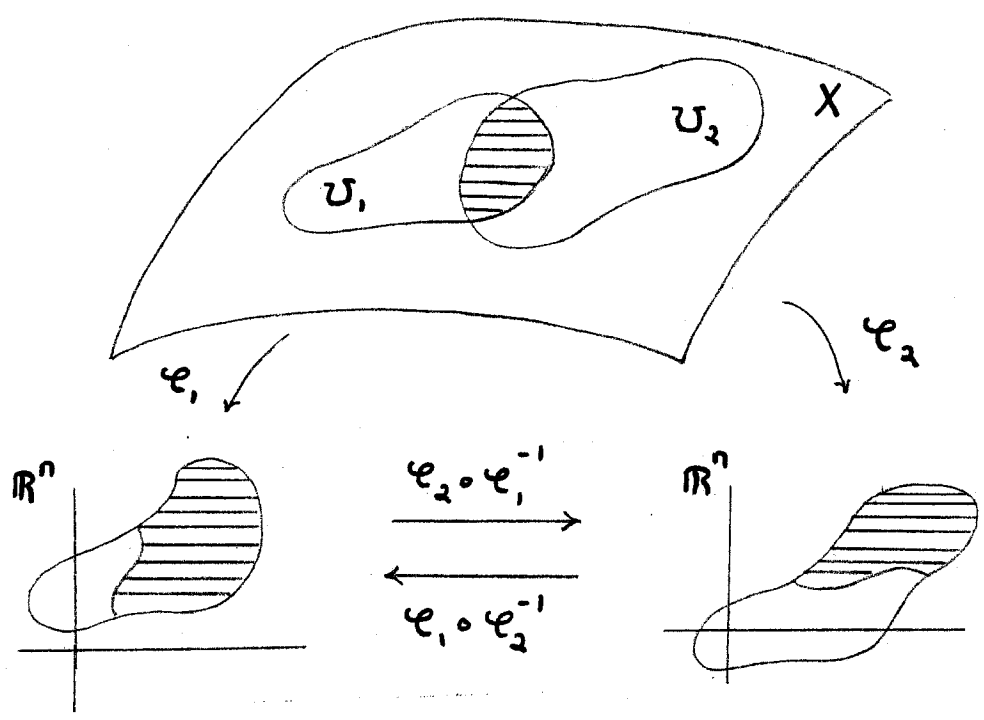
NOTE THAT, FOR POINTS  $x$  IN  $U_S \cap U_N = S^2 - \{N, S\}$ , TWO  
SETS OF COORDINATES HAVE BEEN SUPPLIED, E.G.,

$$\varphi_S\left(\frac{1}{\sqrt{2}}, \frac{1}{2}, \frac{1}{2}\right) = (\sqrt{2}, 1)$$
$$\varphi_N\left(\frac{1}{\sqrt{2}}, \frac{1}{2}, \frac{1}{2}\right) = \left(\frac{\sqrt{2}}{3}, \frac{1}{3}\right)$$

WE WILL NEED THE "COORDINATE TRANSFORMATIONS" THAT RELATE  
THESE TWO.

GENERAL DEFINITION: IF  $(U_1, \varphi_1)$  AND  $(U_2, \varphi_2)$  ARE TWO  
 $n$ -DIMENSIONAL CHARTS ON  $X$  AND  $U_1 \cap U_2 \neq \emptyset$ , THEN  
THE OVERLAP MAPS (OR COORDINATE TRANSFORMATIONS) ARE





$$\varphi_2 \circ \varphi_1^{-1} : \varphi_1(U_1 \cap U_2) \rightarrow \varphi_2(U_1 \cap U_2)$$

$$\varphi_1 \circ \varphi_2^{-1} : \varphi_2(U_1 \cap U_2) \rightarrow \varphi_1(U_1 \cap U_2)$$

THESE ARE (INVERSE) HOMEOMORPHISMS THAT RELATE THE TWO SETS OF COORDINATES PROVIDED POINTS OF  $U_1 \cap U_2$ .

LET'S COMPUTE THE OVERLAP MAPS FOR  $(U_S, \varphi_S)$  AND  $(U_N, \varphi_N)$  ON  $S^2$ :

$$U_S \cap U_N = S^2 - \{N, S\}$$

$$\varphi_S(U_S \cap U_N) = \varphi_N(U_S \cap U_N) = \mathbb{R}^2 - \{(0,0)\}$$

$$\varphi_N \circ \varphi_S^{-1} : \mathbb{R}^2 - \{(0,0)\} \rightarrow \mathbb{R}^2 - \{(0,0)\}$$

$$\varphi_S \circ \varphi_N^{-1} : \mathbb{R}^2 - \{(0,0)\} \rightarrow \mathbb{R}^2 - \{(0,0)\}$$

E.G., FOR  $y = (y^1, y^2) \in \mathbb{R}^2 - \{(0,0)\}$

$$\begin{aligned}
 (\varphi_S \circ \varphi_N^{-1})(y) &= \varphi_S(\varphi_N^{-1}(y^1, y^2)) \\
 &= \varphi_S \left( \frac{2y^1}{1 + \|y\|^2}, \frac{2y^2}{1 + \|y\|^2}, \frac{1 - \|y\|^2}{1 + \|y\|^2} \right) \\
 &= \left( \frac{\frac{2y^1}{1 + \|y\|^2}}{1 - \frac{1 - \|y\|^2}{1 + \|y\|^2}}, \frac{\frac{2y^2}{1 + \|y\|^2}}{1 - \frac{1 - \|y\|^2}{1 + \|y\|^2}} \right) \\
 &= \dots \quad (\text{SOME ALGEBRA}) \\
 &= \left( \frac{y^1}{\|y\|^2}, \frac{y^2}{\|y\|^2} \right) = \frac{1}{\|y\|^2} y
 \end{aligned}$$

SIMILARLY,

$$(\varphi_N \circ \varphi_S^{-1})(y) = \frac{1}{\|y\|^2} y$$

EXERCISE 15 : GENERALIZE ALL OF THIS TO THE  $n$ -SPHERE, I.E., DEFINE STEREOGRAPHIC PROJECTION CHARTS  $(U_S, \varphi_S)$  AND  $(U_N, \varphi_N)$  FROM THE NORTH AND SOUTH POLES OF  $S^n$  AND FIND THE OVERLAP MAPS.

EXERCISE 16 : DEFINE ANOTHER CHART  $(U, \varphi)$  ON  $S^2$  BY "PROJECTING TO OPEN UPPER HEMISPHERE VERTICALLY DOWN", I.E.,

$$U = \{ (x^1, x^2, x^3) \in S^2 : x^3 > 0 \}$$

$$\varphi : U \rightarrow \mathbb{R}^2$$

$$\varphi(x^1, x^2, x^3) = (x^1, x^2)$$

SHOW THAT THIS REALLY IS A CHART ON  $S^2$  AND THEN COMPUTE ITS OVERLAP MAPS WITH  $(U_s, \varphi_s)$ , BEING PARTICULARLY CAREFUL ABOUT THE DOMAINS OF  $\varphi_s \circ \varphi^{-1}$  AND  $\varphi \circ \varphi_s^{-1}$ .

EXERCISE 17 : PROVE THAT EVERY OPEN INTERVAL IN  $\mathbb{R}$  IS HOMEOMORPHIC TO  $\mathbb{R}$ .

EXERCISE 18 : PROVE THAT EVERY  $d$ -OPEN BALL  $U_\varepsilon^d(p)$  IN A METRIC SPACE  $(X, d)$  IS ACTUALLY AN OPEN SET IN THE METRIC TOPOLOGY.